

ECE 265 – LECTURE 14

Analog Signal Acquisition

The A/D converters

Lecture Overview

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- Analog signal acquisition
- The A/D Converters on the 68HC11

- REF: Chapters 7 and 8 plus the 68HC11 reference manual.

Analog signals

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- Analog output is typical of most transducers and sensors.
- Need to convert these analog signals into a digital representation so the microcontroller can use it.
- Some characteristics of analog signals.

Analog signals

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 - ▣ Maximum and minimum voltages

Analog signals

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- Some characteristics of analog signals.
 - ▣ Maximum and minimum voltages
 - ▣ Precise continuous signals

Analog signals

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- Some characteristics of analog signals.
 - ▣ Maximum and minimum voltages
 - ▣ Precise continuous signals
 - ▣ Rate of voltage change

Analog signals

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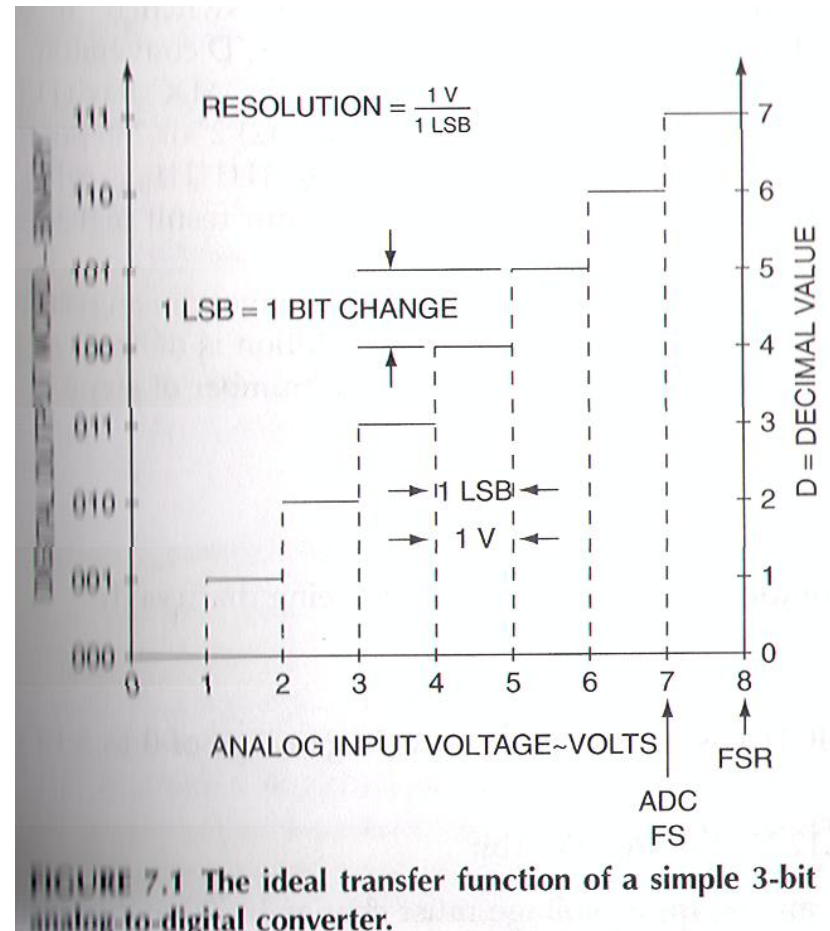
- Analog output is typical of most transducers and sensors.
- Need to convert these analog signals into a digital representation so the microcontroller can use it.

- Some characteristics of analog signals.
 - ▣ Maximum and minimum voltages
 - ▣ Precise continuous signals
 - ▣ Rate of voltage change
 - ▣ Frequency if not a steady state signal

Analog-to-Digital Converters

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- The ideal transfer function of a 3-bit ADC
- Full-scale (input voltage) range (FSR)
- Analog signal is continuous
- Digital – finite and discrete
 - In general n-bit converter
 - Total of 2^n output codes



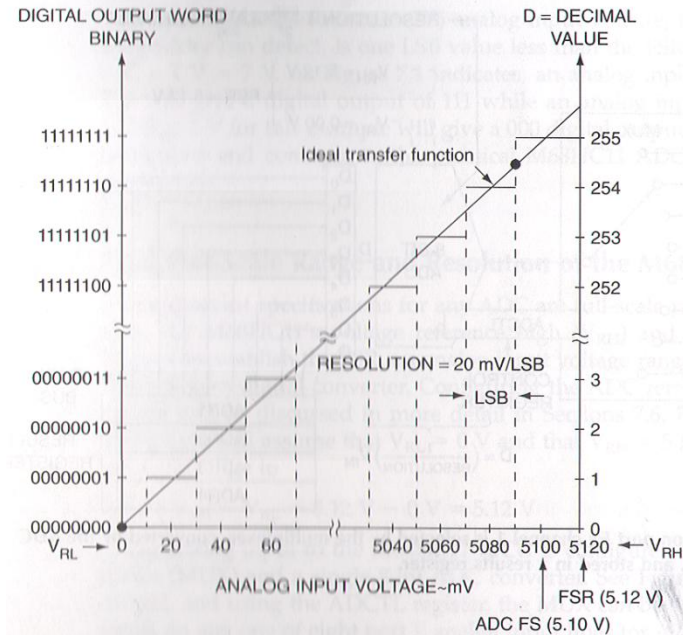
Quantization Error and FS

- The smallest input change that can be detected.
- In the 3 bit example it would be 1 Volt and defines the converters LSB accuracy.
- Another term – Full Scale input – the largest analog voltage that a converter can detect. Voltages greater than the FS input will result in a converted value of 111---11.
- Similarly inputs less than the minimum input voltage result in 000---00.

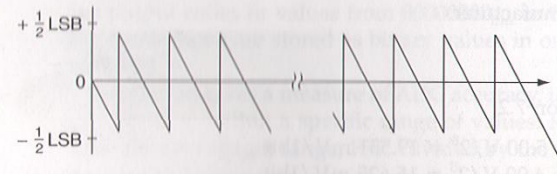
Quantization Error of the 68HC11

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- Graphical view
- Note how discrete values represent the analog signal



(a) THE TRANSFER FUNCTION FOR AN 8-BIT ADC



(b) QUANTIZATION ERROR

FIGURE 7.3 The characteristics of Motorola's M68HC11 8-bit analog-to-digital converter.

The 68HC11

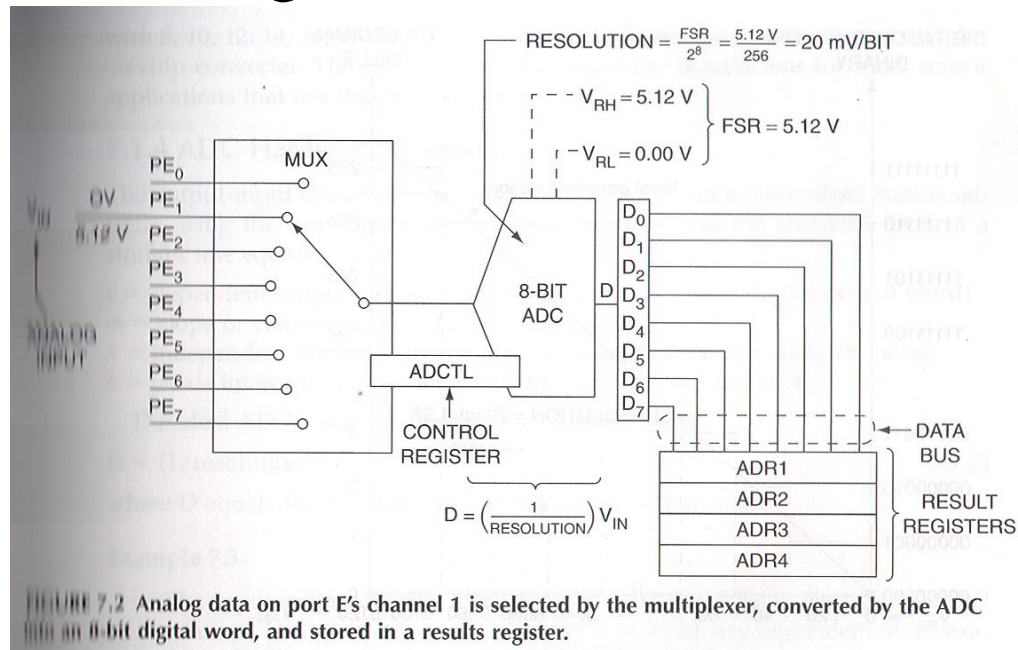
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- The 68HC11 has an 8 bit A/D converter which results in 256 possible digital output values.
- The resolution = $FSR/256$
- The FSR of the 68HC11 is 0 to 5.12V so the resolution is 20mV/1bit
 - ▣ $5.12V/256 = .02031 \text{ V/bit} = 20.3 \text{ mV/bit}$
 - ▣ Meaning – input change of 20mV changes LSB

68HC11 ADRs

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- 68HC11 has 4 A-to-D conversion registers
- When a conversion is done, result is placed in one of the ADR_x registers, where x is 1 to 4.



Math Conversion equation

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- The output-input characteristic equation of an ADC
 - $D = (1/\text{resolution})V_m$
 - Where D is the decimal value of the output word and V_m is the measured voltage.

 - Example (from Ex 7.3)
 - The input voltage is 2.56V – what is the converted digital value?
 - Output
 - $D = (1\text{bit}/20\text{mV})2560\text{mV} = 128$
 - Converting to binary gives $1000\ 0000$ which will be stored in one of the 4 result registers.

Port E and ADR addresses

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- When using Port E as a digital port the port is accessed through address \$100A
- The A/D control register, ADCTL, is at address \$1030
- The ADR registers are at addresses – these are read only registers.
 - ▣ ADR1 - \$1031
 - ▣ ADR2 - \$1032
 - ▣ ADR3 - \$1033
 - ▣ ADR4 - \$1034

ADCTL register

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- To use the A/D converter on the 68HC11 the users only needs to write to ADCTL for the CPU to read results from the register. There are 8 A/D channels but only 4 results from one of the two groups of 4 can be stored at any one time.
 - ▣ Could also use the 4 registers to save 4 conversions from one input pin
- ADCTL register – controls how the A/D converter works and how the registers are used.

The bits in the control register

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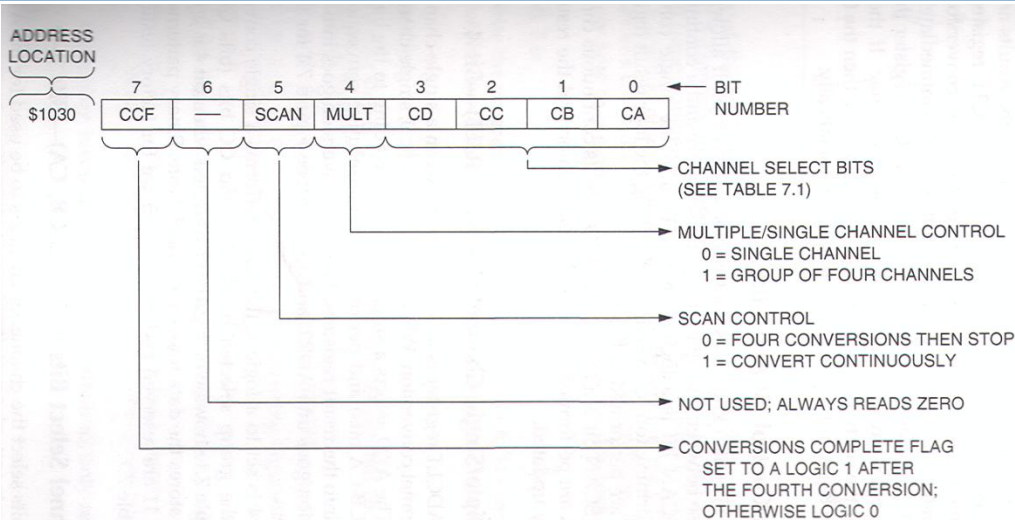


FIGURE 7.6 A/D control and status register (ADCTL).

- Bit 7 – Conversion complete – a read only bit
 - Cleared any time the control register written to
 - Set when the A/D completes the 4th conversion and results stored in registers.
 - Conversion starts immediately after a write to this register. If a conversion was in progress it is aborted to allow the initiation of the new conversion.
 - When set up for continuous conversion results are updated automatically.

Control register continued

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- Bit 6 – unused
- Bit 5 – SCAN
 - Value of 0 – single conversion mode – conversion takes place after a write to the register.
 - Value of 1 – continuous conversion mode – conversions take place in round robin mode on the enabled analog input pins.
- Bit 4 – Multiple/Single Channel Control (MULT)
 - Value of 0 – Single channel – Consecutive conversions results are stored in consecutive ADR_x registers
 - Value of 1 – each pin in the group is converted and the result stored in the ADR register.

More on control register

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- Bits 3,2,1,0 – Channel select bits
 - ▣ For the 48-pin package – only 4 A/D inputs
 - ▣ How the CD, CC, CB, CA control bits work
- The MULT bit says
 - 1 channel or all 4
- Table lists specific group
- and pin(s)

TABLE 7.1 Channel Selection When Bit 4 = 1

CD	CC	CB	CA	Port E	Result Register
0	0	0	0	PE0	ADR1
0	0	0	1	PE1	ADR2
0	0	1	0	PE2	ADR3
0	0	1	1	PE3	ADR4
0	1	0	0	PE4	ADR1
0	1	0	1	PE5	ADR2
0	1	1	0	PE6	ADR3
0	1	1	1	PE7	ADR4

Example of interface setup

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- What configuration is needed in the ADCTL register for the A/D to convert continuously group 0?
- Solution: Bits 7 and 6 are don't cares
- Bit 5 = 1 convert continuously
- Bit 4 = 1 group of 4 channels
- Bits 3 and 2 = 00 group 0, PE0-3
- Bits 1 and 0 are not used.
- Value of xx11 00xx or could store 0011 0000
- \$30

Setup example 2

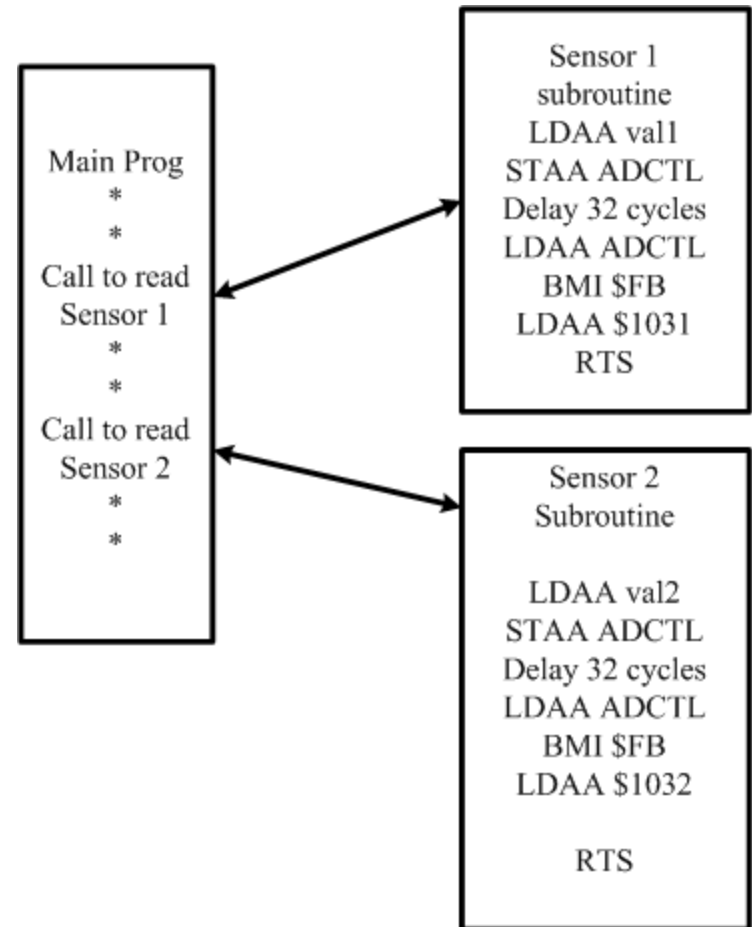
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- What value needs to be written to the ADCTL register to have continuous conversions of pin PE0? What assembler language instructions would you use to set up this?
- Set ADCTL as follows:
 - ▣ Bits 7 and 6 – don't care
 - ▣ Bit 5 – 1 convert continuously val – 0010 0000
 - ▣ Bit 4 – 0 single channel
 - ▣ Bit 3,2,1,0 – 0000 the value for PE0
- The assembler code (assumes A accumulator is free)
 - ▣ LDAA #\$20
 - ▣ STAA \$1030

Example 3

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- Your system has 2 analog sensors. You only need to acquire the value of a given sensor at certain points. How would this be set up.
- Probably through subroutines.
- Specifications of the problem
 - ▣ Sensor 1 – on pin PE0-ADR1
 - ▣ Sensor 2 – on pin PE1-ADR2
- The valx values for the code
 - ▣ val1 – 0010 0000
 - ▣ val2 – 0010 0001
- How is the A/D being set up for conversion?
 - ▣ Could also be done with 0000 0000 and 0000 0001



Signal setup for A/D use

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- The 68HC11 needs 2 reference input voltages.
 - ▣ A low voltage reference – V_{RL} – pin 51
 - ▣ A high voltage reference – V_{RH} – pin 52
- To prevent damage the analog input signals must be current limited.
 - ▣ Input current should not exceed 25mA
- Connect signal through a resistor of value 1k Ω to 10k Ω

Input sensors

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- Transducers, such as pressure, temperature, and acceleration, convert the physical quantity being monitored into an output of voltage, current, or resistance.
- To get the signal to the 68HC11 the signal needs to be a voltage.
- A simple connection for the LM335 temperature sensor can be accomplished.
 - Application circuit from Jameco page.

Lecture summary

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- Use of the 68HC11 A to D converter
 - Basic setup of use
 - The A/D configurations
 - Software setup
 - Interfacing signals

Assignment

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- None